### The results of cutting disks testing for rock destruction

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Abstract. To determine the rational order of disk tools placement on the working body is necessary to know the maximum amount of rock, destroyed by the disk tool in benching cutting mode depending on the tool geometry parameters, physical and mechanical parameters of rocks. The article contains the definition of rational parameters of cutting disk tools as well as power and energy parameters of the destruction process by cutting disks and by executive body of the coal cutter. The rational geometric parameters of cutting discs are specified. It was found that each step of cutting with a minimum depth of penetration has its own maximum height of bench outcrop. The dependence of the volumes of large items destroyed by the disk tool on the cutting step height was determined. The existence of the cyclic alternation of destruction phases, regardless the fracture parameters, the height of the ledge outcrop, and tools like free cutting geometry were found. In contrast to the free cutting in benching mode of destruction two large fragments of rocks in one cycle were observed. Consequently, the cyclical nature of the destruction process in the benching mode will be characterized by two chips and crushing, and this cycling repeats throughout the destruction process with the same parameters of destruction.

### 1 Introduction

At present time studies of mining machinery and equipment increased greatly in coal basin areas of Russia. The reason of this is coal mining boosting in Kuzbass – the greatest Russian coal basin located in Western Siberia. Last decade coal mining in Kuzbass has increase by 6-10 million tons annually. The main part of Kuzbass coal is mined by open pit enterprises - 65%. And now Kuzbass open pits are the leaders in new mining equipment implementation and research contractors [1]. Many studies have focused on the destructive influence of cutting tools on rock arrays [2-5]. Some studies were devoted to the analysis of different aspects of cutting process [6-14].

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Another group of works is devoted to accuracy of measurements [15-18]. Destruction process modelling has become the topic of active research since the 2000<sup>th</sup> [19-24]. Some studies are devoted to applying the results of research of cutting process in different kinds of equipment [25-29]. The significant part of research made by Kuzbass scholars (Western Siberia, Russia) belongs to improving characteristics of cutting instruments for rock destroying in coal mines and pits [30-37].

However production of highly effective cutting disks for rock destroying tools of mining machinery is still important for Kuzbass coal industry.

### 2 Materials and methods

The estimated scheme of the influence model of distributed single effort on a quarter of space with outgrowth is shown in Fig. 1, where the resultant of the force distribution on a horizontal surface is defined as:

$$P = -\int_{0}^{0.1} \int_{0}^{1} (z/l) \left(1 - \cos\frac{2\pi z}{l}\right) dz dx,$$
 (1)

where l – length of contact of the tool with the rock.



Fig. 1. The scheme of the disk tool and the rock interaction

Calculation of models was conducted at following input values:

$$0.01 \le S_c \le 0.09 \text{ m}, S_c \le L \le L^{\infty}$$
 with pitch  $\Delta S_c = \Delta L = 0.005 \text{ m},$  where

 $L^{\infty}$  – unlimited length of the exposed surface.

The fracture surface is described by the criterion:

$$F \leq \frac{\sqrt{2}}{2} \sqrt{\left(\sigma_{1} - \sigma_{2}\right)^{2} + \left(\sigma_{2} - \sigma_{3}\right)^{2} + \left(\sigma_{3} - \sigma_{1}\right)^{2}},$$
 (2)

where  $\sigma_1$ ,  $\sigma_2$ ,  $\sigma_3$  – primary stresses.

The theoretical results describing the volume of the large destroyed element by disk tool are best described by the formula of the ellipsoid.

In Fig. 1 bar and dot-dash lines show the fracture surface, built on the formulae of ellipsoid and the pyramid respectively.

As a result, conducted research showed that the step of cutting  $S_c$  – the distance from the line of action of the tool to the height of the projection influences on the distribution of the fracture surface plane X0Y.

According to the results of modeling, a few dependences were built to define the maximum amount of material destroyed disk tool  $V_{max}$  for cutting step  $S_c$  with unlimited height of projection's exposure (L).

For ellipsoid:

$$V_{el}(S_c) = \begin{cases} \frac{\pi}{3} S_c \left( -36 + \frac{1080}{S_c + 21} \right) \left( 0.1S_c^2 - 0.19S_c + 5.72 \right), \text{ where } 0.03 \le S_c \le 0.09 \text{ m}; \\ \frac{\pi}{3} S_c \left( \frac{1}{2} S_c^2 + \frac{1}{2} S_c + 3 \right) \left( 14.65 - \frac{63.47}{S_c + 4.33} \right), \text{ where } 0 \le S_c \le 0.03 \text{ m}. \end{cases}$$
(3)

For pyramid:

$$V_{pyr}\left(S_{c}\right) = \frac{V_{el}\left(S_{c}\right)}{\pi}.$$
(4)

Results of calculation of the dependence of the volume of large elements (V) destroyed by disk tool on the size of the cutting step S<sub>c</sub> are shown in Fig. 2.



Fig. 2. Dependence of the volume of destroyed large element V and cutting step  $S_c$ 

It is likely that the surface of large elements of real materials having structural defects should be between the fracture surface of the ellipsoid and pyramids. Here, the amount of real materials is shown by the shaded area.

These curves reflect a dome-like character of the distribution. Volumes of maximum large elements separated from the array by disk tool are located in the area of  $0.04 \, m \le S_c \le 0.06 \, m$  and  $0.072 \, m \ge L_{\rm max} \ge 0.04 \, m$ . The maximum amount of large elements is achieved at  $S_c = 0.05 \, m$  and  $L_{\rm max} = 0.055 \, m$ . Therefore if  $0.555 \le S_c / L_{\rm max} \le 1.5$  then maximum area of large elements ( $V_{max}$ ) and maximum is achieved at the ratio of  $S_c / L_{\rm max} = 0.91$ .

In order to confirm the results of simulations there were experimental studies conducted for destruction of sand-and-cement blocks with the following strength characteristics: compressive strength  $\sigma_c = 28.0$  MPa, ultimate tensile strength  $\sigma_t = 4.0$  MPa. The disk instruments had the following geometric parameters: diameter D = 0.16 and 0.18 m; wedge angle F = 30 and 35°. The geometrical dimensions of the projection and fracture parameters had the following values: cutting step  $S_c = 0.03$ , 0.04 and 0.05 m; penetration depth h =0.005, 0.01 and 0.015 m; height of exposure L = 0.03, 0.04 and 0.05 m.

Experimental studies were carried out on a special stand with strain gauge head in the volume setting (Px, Py, Pz), developed in the laboratory of the department of mining machines and equipment of Kuzbass State Technical University [38-40].

As a result of experimental studies the existence of cyclical phase sequence of destruction was revealed, regardless of fracture parameters, the height of projection exposed and geometry of tools like free cutting.

Fig. 3 shows these phases of destruction depending on the different penetration depth (h) of a disk tool. In contrast to free-cutting, in projection mode of destruction we observed two large fragments of rocks in the same cycle. Consequently, the cyclical nature of destruction process in projection mode [41] is characterized by two fragments and common fragmentation, and all these cycles are repeated throughout the process of destruction with the same parameters of fracture.



Fig. 3. Forms of fragments and the cycles of destruction with projection cutting mode

On the basis of conducted experiments it was established that phases of cycles don't depend on penetration depth (h) and have the same form of fragments. Also it was revealed that when changing diameter of the tool D, length of a phase of destruction of  $l_p$  remained constant.

As a result of calculations the following functional dependences of volume of the destroyed large elements of material (V) on a cutting step  $S_c$  and height of exposure of free surface (L) were calculated:

- for ellipsoid:

$$V_{el}(S_c, L) = \begin{cases} \frac{\pi}{6} S_c L \left( 14.65 - \frac{63.47}{S_c + 4.33} \right), \text{ where } 0.03 \le S_c \le 0.09 \text{ m} \\ S_c \le L \le L_{\max} = \frac{1}{2} S_c^2 + \frac{1}{2} S_c + 3, \\ \frac{\pi}{6} S_c L \left( 0.1S_c^2 - 0.19S_c + 5.72 \right), \text{ where } 0.03 \le S_c \le 0.09 \text{ m} \\ S_c \le L \le L_{\max} = -36 + \frac{1080}{21 + S_c} \end{cases}$$
(5)

- for pyramid:

$$V_{pyr}\left(S_{c},L\right) = \frac{V_{el}\left(S_{c},L\right)}{\pi}.$$
(6)

### 3 Results and discussion

Based on the functional relationship described above the chart (Fig. 4) has been plotted to show clearly the amount of damaged material, depending on the cutting step  $S_c$ , and the height of exposed surface (L). In Fig. 4 solid line denotes the amount of damaged material,

calculated on the ellipsoid, and bar line – for the pyramid. The volume of real materials shown as shaded area. The dashed line represents the average volume of destroyed material. It can be seen that the most exposed surface  $L_{max}$  (for each step of cutting) destroyed by the maximum volume is observed for D = 0.04 m, 0.05 m and 0.06 m height to the exposed surface of L = 0.07 m; 0.055 m and 0.04 m, respectively. The greatest value of volume is observed at  $S_c = 0.05$  m and  $L_{max} = 0.055$  m, confirming previously given ratio  $S_c/L_{max} = 0.91$  for  $V_{max}$ .



Fig. 4. Dependence of the volume of destroyed element (V) in one phase of cutting cycle on the height of exposure (L)

We modeled real zone of destruction for outgrowth system of development with working body for the ratio  $S_c/L_{max} = 0.91$  (Fig. 5A), from which it follows that this ratio is characterized by significant area of intact material (indicated by the dashed lines), for further destruction of which the undue increase of energy consumption is required.

Therefore, to achieve the smallest area of intact material while maintaining the maximum possible amount of damaged material we modeled simulated modes and selected the parameters of destruction  $S_c \ge 0.035$  m and L = 0.045 m (Fig. 5B).



Fig. 5. The description of outgrowth disintegration in plane: A – with  $S_c = 0.05$  m,  $L_{max} = 0.055$  m; B – with  $S_c \ge 0.035$  m,  $L_{max} = 0.045$  m.

The results of theoretical and experimental studies of the volume of destruction of large elements (V) depending on depth of introduction (h) are given in fig. 6.



Fig. 6. The results of theoretical and experimental studies of the volume of large elements destruction (V) depending on depth of introduction h.

Horizontal lines in Fig. 6 designate theoretical dependences of volume of destroyed material (*V*) without deepening the disk tool. They are independent from depth of introduction of *h* character and are calculated for a pyramid (Fig.5 A,B, line 1), an ellipsoid ((Fig.5 A,B, line 2) and the average volume of the destroyed element ((Fig.5 A,B, line 3)  $V_{av} = (V_{el} + V_{pyr})/2$ . Results of experimental studies are designated by points depending on the depth of penetration of *h*.

### 4 Conclusions

Results of the maximum volumes of destroyed material  $(V_{max})$  are located between the theoretical dependences calculated on formulas of an ellipsoid and a pyramid. Therefore, the offered theoretical dependences of creation of volumes of destroyed large elements (V) on influence of the disk tool without deepening are correct for depth of introduction of h < 0.015 m. At the destruction of solid rocks the disk tool penetrates into a depth h of 0.01 m. So, defined functional dependencies are valid for the destruction of solid rocks with outgrowth mode by disk tools.

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### Contents

00001 Preface: the role of T.F. Gorbachev State Technical University as the Flagship of Kemerovo Region Innovative Development *A. Krechetov* 

### **Perspective Mining Technologies**

- 01001 The Length Of Bearing Pressure Zone For The Flat Seams Extraction In A Linear Deformation Rock V. Gogolin, Y. Lesin and A. Djagileva
- 01002 The influence of advancing speed of powered mining stope with single face on earth's surface displacing in Kuzbass A. Renev, S. Svirko, A. Bykadorov and V. Fedorin
- 01003 Energy Consumption in the Process of Excavator-Automobile Complexes Distribution at Kuzbass Open Pit Mines I. Panachev, B. Gerike, I. Kuznetsov and A. Shirokolobova
- 01004 Slope Stability Assessment and Underground Mine Design Analysis of Achibo-Sombo Underground Conventional Coal Mine, Southwest Ethiopia *M. Haftu, B. Konka, K. Woldeargay and A. Abay*
- 01005 Geomechanics of rock array for chamber system of coal deposits development on the example of finalizing by KGRP complex
   A. Bykadorov, D. Degtyarev, S. Smirnov and O. Pechenegov
- 01006 Justification of the Optimal Granulometric Composition of Crushed Rocks for Open-Pit Mine Road Surfacing V. Shalamanov, V. Pershin, S. Shabaev and D. Boiko
- 01007 Optimization of transportless technological schemes for coal seams quarrying T. Gvozdkova, E. Plotnikov and E. Usova
- 01008 The features of three- and four-tier internal dumps capacity calculation with the additional capacity preparation in the dump tiers T. Gvozdkova, E. Kuznetsov, A. Rudakova and S. Markov
- 01009 The Relationship Between the Manifestations of Rock Pressure and the Relative Deformation of Surrounding Rocks
   S. Kostyuk, N. Bedarev, O. Lyubimov and A. Shaikhislamov
- 01010 Computer Simulation of Electroosmotic Soils Treatment M. Gucal and A. Pokatilov
- 01011 Innovative numerical modelling of technogenic rock arrays structure S. Markov, M. Tyulenev, O. Litvin and E. Tyuleneva
- 01012 Definition of the form of coal spontaneous combustion source as the inverse problem of geoelectrics

D. Sirota, V. Ivanov and V. Khyamyalyaynen

- 01013 Numerical Simulation of Primary Roof Collapse in Production Workings I. Ermakova and V. Klimov
- 01014 The Study of Processes of Electrochemical Treatment of Soils at the Pilot Test Site S. Prostov, E. Shabanov and A. Shadrin
- 01015 The study of stress-strain state of stabilized layered soil foundations M. Sokolov, S. Prostov and V. Zykov
- 01016 Justification of parameters and technology of retaining prism filling to eliminate landslide
   V. Balakhnin, O. Veretennikova, R. Pobegaylo and E. Mezina
- 01017 Use of Deep Peat-Processing Products for Hydrophobic Modification of Gypsum Binder
  - O. Misnikov and V. Ivanov
- 01018 Software for Automated Production Line of Peat Briquettes V. Lebedev and O. Puhova
- 01019 Assessment process of concept for mining and its impact on the region M. Cehlår, J. Janočko, Z. Šimková and T. Pavlik
- 01020 Experimental Study of Methane Hydrates in Coal V. Smirnov, V. Dyrdin, T. Kim, A. Manakov and A. Khoreshok
- 01021 Expert evaluation of innovation projects of mining enterprises on the basis of methods of system analysis and fuzzy logics
   A. Pimonov, E. Raevskaya and T. Sarapulova
- 01022 Gas hydrates in coal seams and their impact on gas-dynamic processes in underground mining *T. Kim, V. Dyrdin, V. Smirnov and V. Nesterov*

#### **Environment Saving Development of Mining**

- 02001 Environmental and Economic Efficiency of Comprehensive Technology of Sulfur Oxides, Nitrogen Oxides and Mercury Removal from Flue Gases S. Grigashkina, T. Galanina, V. Mikhailov, T. Koroleva and E. Trush
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- 02004 The results of air treatment process modeling at the location of the air curtain in the air suppliers and ventilation shafts

A. Nikolaev, N. Alymenko, A. Kamenskih and V. Nikolaev

02005 Mitigating Against Conflicts in the Kenyan Mining Cycle: Identification of Gaps in the Participation and Recourse for Rights Holders (Civil Society & Community) S. Anyona and B. Rop

### **Innovative Mining Equipment**

- 03001 Modeling of Power Consumption of the Mining Equipment Using "The Probabilistic Automata Method"
  - A. Zakharova, V. Kashirskikh, I. Lobur, N. Shauleva and V. Borovtsov
- 03002 Application of Machine Learning for Dragline Failure Prediction A. Taghizadeh and N. Demirel
- 03003 Kinematic Parameters Of Rotary Transmission With Hydraulic Cylinders M. Blaschuk, A. Dronov, A. Koperchuk, R. Chernukhin and V. Litvinenko
- 03004 The results of cutting disks testing for rock destruction A. Khoreshok, L. Kantovich, V. Kuznetsov, E. Preis and D. Kuziev
- 03005 Grinding efficiency improvement of hydraulic cylinders parts for mining equipment A. Korotkov, V. Korotkov, L. Mametyev, L. Korotkova and T. Terjaeva
- 03006 The Smart Grid using in the Kuzbass open-pit coalmine I. Semykina, A. Evstratov and G. Lebedev
- 03007 Multifunctional Testing Rig for Machinery Safety Equipment S. Vöth, J. Tschersich and Tim Schwartz
- 03008 Development of the preventive maintenance system for belt conveyors reducers B. Gerike, I. Panachev and E. Kuzin
- **03009** Determination of Load Performance of Two-Bar Girder Lining Y. Glazkov, A. Kazantsev, D. Nesteruk, V. Aksenov and A. Efremenkov
- **03010** Ways of increasing excavator fleet productivity in Russian coal open pits (Kuzbass case study)

M. Drygin, N. Kurychkin and A. Bakanov

03011 Strategy of Russian Coal Mining Enterprises' Excavator Park Technical State Correction

M. Drygin, N. Kurychkin and A. Bakanov

- 03012 The innovative development of machine building as a driver of import substitution S. Zhironkin, M. Gasanov, G. Barysheva, K. Kolotov and O. Zhironkina
- 03013 "Smart Service" as an innovative system of service for mining companies in Kuzbass
  - L. Samorodova, L. Shut'ko, Y. Yakunina and O. Lyubimov
- 03014 Special Modes of AC Drives Operation in the Mining Industry

L. Payuk, N. Voronina, O. Galtseva, D. Zhang and A. Rogachev

- 03015 Impact of the number of blades of the geokhod cutting body on cutting forces V. Aksenov, V. Sadovets, E. Rezanova and D. Pashkov
- 03016 Comparison of technological efficiency of gravitational devices for preparation of large diluted coal

V. Udovitsky, V. Kandinsky and A. Begunov

03017 The intelligent mechatronic system for open pit mining to increase the operation life of equipment

I. Semykina, V. Zavyalov and V. Kashirskikh

### **Economic and Social Development of Mining Regions**

- 04001 The principles of municipal industrial clusters' establishment on the territory of advancing social-and-economic development of mono-town
  - O. Ivanova, G. Antonov and S. Bereznev
- 04002 The innovative strategy of social and economic development of mining region S. Bereznev, O. Zonova and E. Lubkova
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V. Mikhalchenko and Y. Rubanik

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  - N. Kudrevatykh, T. Snegireva and A. Tselischeva
- 04007 Theoretical Foundations of the New Industrialization of the Mining Region under Globalization
  - L. Kusurgasheva, O. Nedospasova and E. Zhernov
- 04008 Problems and Prospects of Sustainable Development of Mining Regions I. Levitskaya, N. Pastukhova and O. Dubrovskaya
- 04009 Innovations as borders of stages of coal industry historical development E. Sigareva, S. Popov, S. Baturin, N. Sidorova and M. Borisova
- 04010 Using innovative interactive technologies for forming linguistic competence in global mining education
  - G. Chistyakova, E. Bondareva, K. Demidenko, E. Podgornaya and O. Kadnikova

04011 Technological convergence and innovative development of natural resource economy

F. Agafonov, A. Genin, O. Kalinina, O. Brel and O. Zhironkina

04012 Structural problems of mining region innovative development (Kuzbass, Western Siberia)

E. Dotsenko and N. Ezdina

04013 Neo-industrialization of Kuzbass economy in innovative development of coal industry and machinery

A. Balabanova, V. Balabanov, E. Dotsenko and N. Ezdina

04014 The problems of correlation the life quality and interpersonal dialogue in legal practice of mining regions

V. Zolotukhin, E. Stepantsova, M. Kozyreva, A. Tarasenko and A. Stepantsov

04015 Demographic and migration policy in the mining region and its impact on the ecological consciousness of the population

V. Zolotukhin, A. Bel'kov, E. Stepantsova, M. Kozyreva and A. Tarasenko

04016 Cross-cultural analysis of the verbal conflict behavior of the graduate mining engineers

I. Pevneva, O. Gavrishina, A. Rolgayzer, M. Agienko and A. Myaskov

- 04017 The impact of human factor on labor productivity at the mining enterprises G. Pinigina, I. Kondrina, S. Smagina, V. Tatsienko and A. Meshkov
- 04018 Enhancing the Role of Educational Services of Higher Education System in the Competitive Specialists Training for Industry O. Kuznetsova, S. Kuznetsova, E. Yumaev, V. Kuznetsov and I. Plotnikova
- 04019 Formation and Development of the Training System for Innovative Development of Regional Industry

O. Kuznetsova, S. Kuznetsova, E. Yumaev, V. Kuznetsov and O. Galtseva

04020 Evaluating the Effectiveness of Internal Corporate Controls in Coal Mines Illustrated By the Example of JSC "SUEK-Kuzbass"

E. Kucherova, T. Ponkratova, T. Tyuleneva and N. Cherepanova

04021 The communication aspect of specialists' professional competence L. Znikina, N. Mamontova and P. Strelnikov

### volume 15 - 2017

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